

# Radar Estimation Algorithm Using Neural Network Approach

許順棚、鍾翼能

E-mail: 9605040@mail.dyu.edu.tw

## ABSTRACT

The multiple-target tracking algorithm is more important than that of tracking single target in a radar system. It will solve the problems of between radar measurements and existing targets. There is one new data association technique denoted Competitive Hopfield Neural Network (CHNN) is investigated in this thesis. It will take care of the computation of the relationships and to obtain the better tracking results. In order to compare the performance of the radar tracking algorithm, there are three approaches which are Multiple Model Estimator, One-Step Conditional Maximum Likelihood, and Maneuvering Estimation are conducted. According to the simulation results, we know that the performance of the proposed approach is the best one.

Keywords : Neural network ; maneuvering ; Data association

## Table of Contents

目錄 封面內頁 簽名頁 授權書 . . . . .	iii 中文摘要 . . . . .
iv 英文摘要 . . . . .	v 誌謝 . . . . .
vi 目錄 . . . . .	vii 圖目錄 . . . . .
x 表目錄 . . . . .	xii 第一章 諸論 1.1研究動機與背景 . . . . .
1.1.2 研究方法 . . . . .	2 1.3論文章節結構 . . . . .
3 第二章 類神經網路之理論 2.1簡介 . . . . .	5 2.2 ANN之優點 . . . . .
5 2.2.1可以應用的領域非常廣 . . . . .	, 5 2.2.2具有多層輸入輸出之系統 . . . . .
, 5 2.2.3具有過濾資料之能力 . . . . .	, 6 2.2.4具有適應性之學習能力 . . . . .
, 6 2.3神經元模型 . . . . .	7 2.4類神經網路結構 . . . . .
10 2.5循環之網路 . . . . .	11 2.6離散型Hopfield之網路 . . . . .
13 第三章 卡門濾波器 3.1卡門濾波器簡介 . . . . .	16 3.2卡門濾波器之線性系統模式 . . . . .
23 3.3卡門濾波器之數學運算 . . . . .	19 3.4卡門濾波器之相關特性 . . . . .
25 第四章 多目標追蹤應用資料相關結合技術 4.1前言 . . . . .	30 4.2.1目標追蹤起始 . . . . .
30 4.2多目標追蹤程序 . . . . .	31 4.2.2目標追蹤相互關係 . . . . .
, 31 4.2.3目標軌跡更新 . . . . .	32 4.2.4目標軌跡估測 . . . . .
, 33 4.2.5目標軌跡刪除 . . . . .	34 4.3 資料相關結合 . . . . .
, 35 4.3.1 Gating理論 . . . . .	35 4.3.2競爭式Hopfield 網路演算法 . . . . .
41 4.3.4競爭式Hopfield 網路演算法結合機率 . . . . .	, 38 4.3.3 One-Step Conditional Maximum Likelihood . .
46 5.2多目標追蹤系統之數學模式的建立 . . . . .	46 5.3變速度追蹤理論 . . . . .
56 5.4.1動態系統之模型 . . . . .	50 5.4.2變速度目標偵測與追蹤技術 . . . . .
56 5.4.2變速度目標偵測與追蹤技術 . . . . .	60 第六章 電腦模擬結果與分析 6.1前言 . . . . .
69 6.3 變速度雙目標追蹤模擬分析 . . . . .	67 6.2變速度單目標追蹤模擬分析 . . . . .
79 第七章 結論 . . . . .	74 6.4 變速度四目標追蹤模擬分析 . . . . .
87 圖目錄 圖2.1 神經元的架構 . . . . .	86 參考文獻 . . . . .
10 圖2.3 循環網路 . . . . .	7 圖2.2 個神經元組成的層 . . . . .
12 圖2.5 Hopfield 網路結構 . . . . .	12 圖2.4 延時方塊 . . . . .
16 圖3.2 卡門濾波器 . . . . .	13 圖3.1 卡門濾波器之系統流程圖 . . . . .
29 圖3.4 卡門濾波器之運作流程圖 . . . . .	22 圖3.3 卡門濾波器之動態系統模型 . . . . .
31 圖4.1 多目標系統之工作流程圖 . . . . .	29 圖4.1 多目標系統之工作流程圖 . . . . .
32 圖4.3 多目標追蹤之幾何圖形 . . . . .	32 圖4.2 追蹤初始相互關係判別圖 . . . . .
35 圖4.5 目標物與量測值關係之Gates示意圖 . . . . .	33 圖4.4 追蹤程序之基本流程圖 . . . . .
38 圖5.1 變速度追蹤理論流程圖 . . . . .	36 圖4.6 目標軌跡與量測值示意圖 . . . . .
55 圖5.3 The IMM Algorithm . . . . .	47 圖5.2 變速度追蹤適應性濾波器架構 . . . . .

56 圖6.1 演算法一的單目標追蹤圖 . . . . .	70 圖6.2 演算法一的單目標誤差圖 . . . . .
70 圖6.3 演算法二的單目標追蹤圖 . . . . .	71 圖6.4 演算法二的單目標誤差圖 . . . . .
71 圖6.5 演算法三的單目標追蹤圖 . . . . .	72 圖6.6 演算法三的單目標誤差圖 . . . . .
72 圖6.7 演算法四的單目標追蹤圖 . . . . .	73 圖6.8 演算法四的單目標誤差圖 . . . . .
73 圖6.9 演算法一的雙目標追蹤圖 . . . . .	75 圖6.10 演算法一的雙目標誤差圖 . . . . .
76 圖6.11 演算法二的雙目標追蹤圖 . . . . .	77 圖6.12 演算法二的雙目標誤差圖 . . . . .
77 圖6.13 演算法三的雙目標追蹤圖 . . . . .	78 圖6.14 演算法三的雙目標誤差圖 . . . . .
78 圖6.15 演算法四的雙目標追蹤圖 . . . . .	79 圖6.16 演算法四的雙目標誤差圖 . . . . .
81 圖6.17 演算法一的四目標追蹤圖 . . . . .	81 圖6.18 演算法一的四目標誤差圖 . . . . .
82 圖6.19 演算法二的四目標追蹤圖 . . . . .	82 圖6.20 演算法二的四目標誤差圖 . . . . .
83 圖6.21 演算法三的四目標追蹤圖 . . . . .	83 圖6.22 演算法三的四目標誤差圖 . . . . .
83 圖6.23 演算法四的四目標追蹤圖 . . . . .	84 圖6.24 演算法四的四目標誤差圖 . . . . .
. 84 表目錄 表3.1 DISCRETE-TIME KALMAN FILTER EQUATIONS . . . . .	, 28 表6.1 單目標運動量之初始值 . . . . .
. . . . .	69 表6.2 單目標之變速度區間設定 . . . . .
. . . . .	69 表6.3 演算法一、二、三、四之單目標誤差比較結果 . . . . .
. . . . .	69 表6.4 雙目標運動量之初始值 . . . . .
. . . . .	74 表6.5 雙目標之變速度區間設定 . . . . .
. . . . .	74 表6.6 演算法一、二、三、四之雙目標誤差比較結果 . . . . .
. . . . .	75 表6.7 四目標運動量之初始值 . . . . .
. . . . .	79 表6.8 四目標之變速度區間設定 . . . . .
. . . . .	. 80 表6.9 演算法一、二、三、四之四目標誤差比較結果 . . . . .

## REFERENCES

1. S. Blackman, " Multiple Target Tracking With Radar Applications," Artech House, 1986.
2. Y. Bar-Shalom, and T.E. Formann, " Tracking and Data Association," Artech House, 1988.
3. Y.N. Chung, D.L. Gustafson, and E. Emre, " Extended Solution to Multiple Maneuvering Target Tracking," IEEE Trans. Aerosp. Electron. Syst. Vol. AES-25, pp.876-887,1990.
4. Y.N. Chung and Y.N. Hu, " A Decentralized Estimation Approach for Target Tracking Problems," to appear in Journal of Control Systems and Technology, Vol. 1, No. 4, 1993.
5. Y. Bar-Shalom and T. Edsion, " Sonar Tracking of Multiple Targets Using Joint Probabilistic Data Association," IEEE Journal of Oceanengg Engineering, Vol. OE-8, No.3, 1983.
6. S. Kingsley and S. Quegan., " Understand Radar Systems," McGRAW-HILL book Co.1992.
7. E. Emre, and J. Seo, " A Unifying Approach to Multi-Target Tracking , " IEEE. Trans. Aerosp. Electron. Syst., Vol. AES-25, pp. 520-528, 1989.
8. R.A. Singer, " Estimating Optimal Tracking Filter Performance for Manned Maneuvering Targets," IEEE Trans. On Aerosp. and Electron. Syst., Vol. AES-5, pp. 473-483, July 1970.
9. Bar-Shalom, Y., " Tracking Methods in a Multi-Target Environment," IEEE Trans. Automa. Contr. , Vol., AC-23, pp. 618-626, Aug.1978.
10. Stein, J. J. , and S.S. Blackman , " Generalized Correlation of Multi-Target Tracking Data," IEEE Transactions on Aerospace and Electronic Systems, AES-II, Nov. 1975, pp. 1207-1217.
11. Sea, R. G., " Optimal Correlation of Sensor Data with Tracks in Surveillance Systems," Proceeding of Sixth International Conference on Systems Sciences, Jan. 9-11, 1973, Honolulu, HI, pp.424-426.
12. Fortmann, T. E., and S. Baron, " Problems in Multi-Target Sonar Tracking," Proceeding of the 1978 IEEE Conference on Decision and Control, San Diego., CA, Jan. 1979, pp.1182-1188.
13. Chang, K. C., Chong, C.Y., and Bar-Shalom, Y., " Joint Probabilistic Data Association in Distributed Sensor Networks," IEEE Trans. Automa. Contr., Vol. AC-31, pp. 889-897, Oct. 1986.
14. Bullock, T. E., Sangsuk-Iam, S., Pietsch, R., and Boudresu, E. J., " Sensor Fusion Applied to System Performance Under Sensor Failures," Proceedings of SPIE. Vol. 931, Sensor Fusion, 1988.
15. Reid, D. B., " An Algorithm for Tracking Multiple Targets," IEEE Trans. Automa. Contr., Vol. AC-24, pp. 843-854, Dec. 1979.
16. R. A. Singer, and K.W. Behnke, " Real-Time Tracking Filter Evaluation and Selection for Tactical Applications," IEEE Trans. on Aerosp. and Electron. Sys., Vol. AES-7, No.1, pp. 100-110, March 1970.
17. B.D.O. Anderson , and J.B. Moore, " Optimal Filtering," Prentice Hall Inc., 1979.
18. A.Farine, and F. A. Studer, " Radar Data Processing," Research Studies Press Ltd., 1985.
19. Byron, Eddle., " Radar Principles, Technology, Applications," Prentice-Hall Inc. 1993.
20. S. Haykin, " Adaptive Filter Theory," Prentice-Hall Inc.1991.
21. Hovanessian, S. A., " Radar System Design and Analysis," Artech House, Inc., 1984.
22. P.D.Hanlon and P.S. Maybeck,"Interrelation Ship of Single-Filter and Multiple-Model Adaptive Algorithms,"IEEE Trans. Aerosp. Electron. Syst. Vol. AES-34,PP.934-946,1998.
23. R.L.Popp,K.R.Pattipati,Y.Bar-Shalom&M.Ysddanapudi, "Parallelization of a Multiple Tracking Algorithm with Superlinear Speedups,"IEEE Trans. Aerosp. Electron. Syst. 24. K. Mehrotra & P.R.Mahapatra, "A Jerk Model for Tracking Highly Maneuvering Targets," IEEE Trans. Aerosp. Electron. Syst. Vol AES-33,pp.1094-1106 ,1997.
25. Pau-Choo Chung, Ching-Tsorng Tsai, E-Ling Chen and Yung-Nien Sun " Polygonal Approximation Using A Competitive Hopfield Neural Network ", Patten Recognition, Vol.27,No.11, pp,1505-1215,1994
26. Neural Networks Algorithms, Applications, and Programming Techniques James A. Freman/David M.Skapora. Addison Wesley
27. Neural NetworkDesign Matin T.hagan, Howard B.Demuth, Mark Beale THOMSON
28. D. J. Kershaw & R. J.Evans, "Waveform Selective Probabilistic Data Association," IEEE Trans. Aerosp. Electron. Syst. Vol . AES-33, pp.1180-1189,1997.
29. S-T.Park&J.G.Lee,"Design of a Practical Tracking Algorithm with Radar Measurements,"IEEE Trans. Aerosp. Electron. Syst. Vol AES-34, pp. 1337-1345, 1998.
30. E.Mazor,J Dayan,A.Averbuch

&Y.Bar-Shalom,"Interacting m Multiple Model Methods in Target Tracking: A Survey," IEEE Trans. Aerosp. Electron. Syst. Vol AES-34,pp.103-124,1998. 31. R.E.Bethel & G.J.Paras, "A PDF Multisensor Multitarget Tracker,"IEEE Trans. Aerosp. Electron. Syst. Vol AES-34,pp.153-169,1998. 32. H.Lee & I-J Tahk,"Generalized Input-Estimation Technique for Tracking Maneuvering Targets, " IEEE Trans. Aerosp. Electron. Syst. Vol AES-35,pp.1388-1403,1999. 33. P.Swerling , " Radar Probability of Detection for Some Additional Fluctuating Target Cases , "IEEE Trans. Aerosp. Electron. Syst. Vol AES-33,pp.698-709,1997. 34. Y.N. Chung and M.T. Lin , " A Multi-Target Tracking Algorithm Using Variable Sampling Rate , " J. of Control. Vol.3, No.1, PP.33-41,1995. 35. N.Okello & B.Ristic, " Maximum Likelihood Registration for Multiple Dissimilar Sensors, " IEEE Trans. Aerosp. Electron.Syst.Vol.39,No.3, pp.1074-1083,2003.