雷達適應性與穩定性分析

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摘 要

雷達追蹤系統變速度偵測技術必須詳加考慮，不然系統將產生巨大的誤差，甚至無法完成追蹤任務。本論文提出一種適應性偵測器,來做多重變速移動式目標追蹤，以結合不同位置的動態偵測器資料，此演算式運用一個適應性的濾波器與資料融合技術，改善追蹤上的問題，進而產生一個總體的估測值。此外本論文亦加入適應性程序進行適應性及穩定性分析。模擬結果顯示本論文之演算法則將使追蹤系統獲得更精確的追蹤結果，並驗證此追蹤系統的效率確有提升，電腦模擬結果顯示，此法可以成功而精確地追蹤多重目標。

關鍵詞 : 變速度偵測 ; 適應性濾波器 ; 適應性及穩定性分析

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