

Applying Neural Network Computing Algorithm to Radar Multiple Target Tracking Systems

陳信達、鍾翼能

E-mail: 9512339@mail.dyu.edu.tw

ABSTRACT

As the developing of technology, multiple-target tracking system is an important subject in both national defense and civil application. In order to manage the complicated radar system, enhancing the performance of system is necessary indeed. The main part of the system is data association. While tracking multiple moving targets, data association can find the connection between radar measurement and trajectory. In usual, the wrong data association will lead to the error of target trajectory and cause the loss. Therefore, in this thesis, a new tracking algorithm Competitive Hopfield Neural Network which is based on the radar target tracking system will efficiently determent the connection of radar measurement and object trajectory and further more to estimate the object position or other related information. By adapting Kalman filter estimation system, CHNN will obtain the great estimate; moreover, with the adaptive procedure tracking technique, the problem of maneuvering will be solved successfully. As the results of this simulation, this thesis conducts that CHNN can not only apply to the multiple target tracking system but also solves the problem of data association and tracking subjects.

Keywords : Data Association ; Competitive Hopfield Neural Network ; Adaptive Procedure

Table of Contents

目錄 封面內頁 簽名頁 授權書	iii 中文摘要
iv 英文摘要	v 誌謝
vi 目錄	vii 圖目錄
x 表目錄	
xiii 第一章 緒論 1.1研究動機與目的	1 1.2研究方法與步驟
2 1.3論文結構	4 第二章 理論架構 2.1卡門濾波器
6 2.2線性卡門濾波器模型	8 2.3卡門濾波器之數學運算
10 2.4擴展式卡門濾波器	12 2.5卡門濾波器之相關特性
2.6多目標追蹤程序	17 2.7類神經網路濾波法
系統簡介	21 2.8雷達
32 3.2類神經網路簡介	24 第三章 類神經網路數學架構 3.1前言
35 3.4循環網路架構	33 3.3類神經網路理論
第四章 Data Association 架構 4.1前言	40 3.5 Hopfield類神經網路
44 4.31-Step Conditional Maximum Likelihood理論	41 44 4.2 JPDA理論
Hopfield Neural Network Algorithm)	53 4.4競爭型類神經網路演算法(Competitive
61 第五章 適應性變速度理論 5.1前言	55 4.5理論證明
65 5.3多感測資料融合(Multiple Sensor Data Fusion)	64 5.2適應性程序
70 6.2變速度單一目標追蹤模擬分析	67 第六章 電腦模擬與分析 6.1前言
79 6.4變速度三目標追蹤模擬分析	73 6.3變速度雙目標追蹤模擬分析
91 第七章 結論	85 6.5變速度四目標追蹤模擬分析
99	98 參考文獻

REFERENCES

1. Y. Bar-Shalom and T.E Fortmann, "Tracking Data and Association," Mathematics in Science and Engineering, Vol.179, 1988.
2. K.C. Chang, C.Y. Chong, and Y. Bar-Shalom, "Joint Probabilistic Data and Association Distributed Sensor Networks," IEEE Trans. Auto-ma. Contr., Vol.AC-31, pp.889-897, Oct. 1986.
3. Y. Bar-Shalom and T. Edision, "Sonar Tracking of Multiple Targets Using Joint Probabilistic Data Association," IEEE Journal of Oceaning Engineering, Vol. OE-8, No.3, July. 1983.
4. Y. Bar-Shalom and T.E. Fortmann, "Tracking and Data Association," Academic Press, INC. 1989.
5. Blackman, S. S., "Multiple Target Tracking with Radar Applications", Artech House, Dedham, Ma., 1986.
6. Y.N. Chung, D.L. Gustafson, and E. Emre, "Extended Solution to Multiple Maneuvering Target Tracking," IEEE Trans. Aerosp.

Electron. Syst., Vol. AES-25, pp.876-887, 1990. 7. E. Emre and J. Seo, "A Unifying Approach to Multi-Target Tracking," IEEE Trans. Aerosp. Electron. Syst., Vol.AES-25, pp.520-528, 1989. 8. Y.N. Chung and M.T. Lin, "A Multi-Target Tracking Algorithm Using Variable Sampling Rate," J. of Control., Vol.3, No.1, pp.33-41, 1995. 9. P.D. Hanlon and P.S. Maybeck, "Interrelation Ship of Single-Filter and Multiple-Model Adaptive Algorithms," IEEE Trans. Aerosp. Electron. Syst., Vol. AES-34, pp.934-946, 1998. 10. E. Mazor, J. Dayan, A. Averbuch, and Y. Bar-Shalom, "Interacting Multiple Model Methods in Target Tracking: A Survey," IEEE Trans. Aerosp. Electron. Syst., Vol. AES-34, pp.103-124, 1998. 11. H. Lee and I.J. Tahk, "Generalized Input-Estimation Technique for Tracking Maneuvering Targets," IEEE Trans. Aerosp. Electron. Syst., Vol.AES-35, pp.1388-1403, 1999. 12. K.A. Fisher and P.S. Maybeck, "Multiple Adaptive Estimation with Filter Spawning," IEEE Trans. Aerosp. Electron. Syst., Vol.38, No.3, pp.755-768, 2002. 13. N. Okello and B. Ristic, "Maximum Likelihood Registration for Multiple Dissimilar Sensors," IEEE Trans. Aerosp. Electron. Syst., Vol.39, No.3, pp.1074-1083, 2003. 14. Blackman, and S. S, "Multiple hypothesis tracking for multiple target tracking," IEEE Aerosp. Electron. Syst., Vol.19, pp.5-18, Jan 2004. 15. Hue, C.; Le Cadre, J.-P.; Perez, P.; "Sequential Monte Carlo methods for multiple target tracking and data fusion" IEEE Trans. on Vol.50, pp.309-325, Feb. 2002. 16. D. Sengupta and R. A. Iltis, "Neural solution to the multitarget tracking data association problem", IEEE Trans. Aerosp. Electron. Syst., 25, pp.86-108, 1989. 17. B. Zhou and N.K. Bose, "A comprehensive analysis of neural solution to the multi target tracking data association problem", IEEE Trans. Aerosp. Electron. Syst., 29, pp.260-263, 1993. 18. L. Chin, "Application of neural networks in target tracking data fusion", IEEE Trans. Aerosp. Electron. Syst., 30, pp.281-287, 1994. 19. P.C. Chung, C.T. Tsai, E.L. Chen and Y.N. Sun, "Polygonal Approximation Using A Competitive Hopfield Neural Network," Pattern Recognition, Vol.27, No.11, pp.1505-1512, 1994. 20. Chuan-Yu Chang and Pau-Choo Chung, "Medical Image Segmentation Using a Contextual-Constraint Based Hopfield Neural Cube," Image and Vision Computing, Vol. 19, pp.669-678, 2001. 21. Pau-Choo Chung, Ching-Tsorng, Tsai, E-Ling Chen, and Yung-Nien Sun, "Polygonal Approximation Using A Competitive Hopfield Neural Network" Patten Recognition, Vol.27, No.11, pp.1505-1215, 1994. 22. H. K. Kwan and C. K. Lee, "A neural network approach to pulse radar detection," IEEE Trans. Aerosp. Electron. Syst., vol. AES-29, pp. 9-21, Jan. 1993. 23. M. K. Sundareshan and F. Amoozegar, "Neural network fusion capabilities for efficient implementation of tracking algorithms," Opt. Eng., vol. 36, no.3, pp. 692-707, Mar. 1997. 24. F. Amoozegar, "Neural-network-based target tracking state-of-the-art survey," Opt. Eng., vol. 37, no. 3, pp. 836-846, Mar. 1998. 25. Cortina, E., and Otero, D., "Maneuvering Target Tracking Using Extended Kalman Filter," IEEE Trans. Aerospace and Electronic Systems, vol. AES-27, pp.155-158, Jan. 1991. 26. Y. Bar-Shalom, K. Birmiwal, "Variable Dimension Filter for Maneuvering Target Tracking," IEEE Trans. Aerosp. Electron. Syst., vol. AES-18, no. 5, pp. 621-629, Sep. 1982. 27. C. B. Chang and J. A. Tabackzynski, "Application of State Estimation to Target Tracking," IEEE Trans. Automatic Control, vol. AC-29, no. 2, pp. 98-109, Feb. 1984. 28. M. Efe and D. P. Atherton, "Maneuvering target tracking with an adaptive Kalman filter," in Proc. 37th IEEE Conf. Decision Contr., Tampa, FL, Dec. pp. 737-742, 1998. 29. T. Tao, "A neural decision estimator for maneuvering targets," in Proc. IEEE Int. Conf. Neural Networks (ICNN ' 94), pp. 3926-3931, 1994. 30. S. Blackman and R. Popoli, "Design and Analysis of Modern Tracking System," Artech House, 1999. 31. F. L. Luo and R. Unbehauen, "Applied Neural Networks for Signal Processing," Peninsula Publishing, 1985. 32. Bar-Shalom Y., and Li, X., "Multi-target multi-sensor tracking: principle and techniques," Storrs, CT: YBS publishing, 1995. 33. M. I. Skolnik, "Introduction to Radar Systems," McGraw-Hill, 1980. 34. D. K. Barton and S. A. Leonov, "Radar Technology Encyclopedia," Artech House, 1997. 35. J. L. Eaves and E. K. Reedy, "Principles of Modern Radar," Van Nostrand Reinhold, 1987. 36. "Neural Networks Algorithms, Applications, and Programming Techniques" James A. Freeman/David M. Skapora. Addison Wiley. 37. "Neural Network Design" Matin T.hagan, Howard B.Demuth, Mark Beale THOMSON. 38. Hovanessian, S. A., "Radar System Design and Analysis," Artech House, Inc. 1984. 39. S. Haykin, "Adaptive Filter Theory," Prentice-Hall Inc. 1991. 40. Byron, Eddle., "Radar Principles, Technology, Applications," Prentice-Hall Inc. 1993. 41. A.Farine, and F. A. Studer, "Radar Data Processing", Research Studies Press Ltd. 1985. 42. B.D.O. Anderson, and J.B. Moore, "Optimal Filtering", Prentice Hall Inc. 1979.