

# The Study of Dynamic Analysis for Steer-by-Wire System

張竣凱、張舜長

E-mail: 9511432@mail.dyu.edu.tw

## ABSTRACT

The main purpose of this study is focus on parameters sensitivity for steer-by-wire system ( SBW ). This paper is setting up the dynamic model of SBW system, and according the dynamic model to analysis the sensitivity of parameter of this system, and analyzing the stability of the SBW when the vehicle steering. When the change of the tire pressure and temperature or the road surface has jolt irregular, it can make the vehicle steering unstably. The parameter pneumatic trail (tp) has a relationship with above-mentioned conditions. The vehicle speed (v) has a relationship with steering. In this paper, there three parameters: pneumatic trail (tp), friction coefficient of road ( $\mu$ ) and vehicle speed (v) will be studied on sensitivity of slip angle, yaw rate, steering angle and steering angle rate for this system. According the result of sensitivity to simulation for the SBW system when the tp、 $\mu$  and v have change.

Keywords : SBW system ; Sensitivity equations

## Table of Contents

目錄 封面內頁 簽名頁 博碩士論文暨電子檔案上網授權書 iii 中文摘要 iv 英文摘要 v 誌謝 vi 目錄 vii 圖目錄 ix 表目錄 xiv 符號說明 xv 第一章 緒論 1.2 文獻回顧 2 1.3 研究目的及架構 3 第二章 車輛線控轉向系統動態數學模型 2.2 半車模型和全車模型轉向系統 16 2.3 二輪半車線控轉向車輛動態穩定度分析 20 2.4 使用Carsim軟體模擬車輛動態 23 第三章 線控轉向系統參數靈敏度之分析 3.1 二輪半車線控轉向系統靈敏度分析 25 3.2 四輪全車線控轉向系統靈敏度分析 29 3.3 半車線控轉向系統參數靈敏度結果與討論 33 3.4 全車線控轉向系統參數靈敏度結果與討論 57 第四章 線控轉向系統動態模擬結果與討論 4.1 半車和全車線控轉向系統模擬結果與討論 82 4.2 在低摩擦路面下， $\mu$ 、tp和v對車輛動態的影響 91 4.3 在高摩擦路面下， $\mu$ 、tp和v對車輛動態的影響 99 4.4 比較與討論  $\mu$ 、tp和v對車輛動態的影響 106 第五章 結論與建議 5.1 結論 109 5.2 建議事項 110 參考文獻 111

## REFERENCES

- 參考文獻 [1] Motoaki Hosaka and Toshiyuki Murakami, "Yaw Rate Control of Electric Vehicle Using Steer-by-Wire System", IEE, AMC, 2004-Kawasaki, pp.31-34, Japan.
- [2] Paul Yih, Jihan Ryu and J. Christian Gerdes, "Vehicle State Estimation Using Steering Torque", AACC, Proc. of the 2004 American Control Conference, Boston, Massachusetts USA, June 30-July 2, 2004.
- [3] Eiichi Ono, Shigeyuki Hosoe, Hoang D. Tuan and Shunichi Doi, "Bifurcation in Vehicle Dynamics and Robust Front Wheel Steering Control", IEE Trans. Contr. Syst. Technol., vol. 6, NO. 3, May, 1998.
- [4] S. Horiuchi, K. Okada and S. Nohtomi, "Improvement of Vehicle Handling by Nonlinear Integrated Control of Four Wheel Torque", JSAE Review 20, pp. 459-464, 1999.
- [5] Sam Sang You and Seok Kwon Jeong, "Controller Design and Analysis for Automatic Steering of Passenger Cars", IEE, Mechatronics 12, pp. 427-446, 2002.
- [6] Bruno Catino, Stefania Santini and Mario di Bernardo, "MCS Adaptive Control of Vehicle Dynamics: an Application of Bifurcation Techniques to Control System Design", IEE, Proc. of the 42nd Conference on Decision and Control, Maui, Hawaii USA, pp. 2252-2257, December 2003.
- [7] Nuksit Noomwongs, Hidehisa Yoshida, Masao Nagai, Katsuhiko Kobayashi and Takashi Yokoi, "Study on Handling and Stability Using Ture Hardware-in-the-Loop Simulator", JSAE Review 24, pp. 457-464, 2003.
- [8] Hyo-Jun Kim and Young-Pil Park, "Investigation of Robust Roll Motion Control Considering Varying Speed and Actuator Dynamics", IEE, Mechatronics 14, pp. 35-54, 2004.
- [9] E. Bakker, L. Nyborg and H. B. Pacejka, "Tyre Modelling for Use in Vehicle Dynamics Studies", SAE Paper No.870421, 1987.
- [10] A. Stotsky and X. Hu, "Stability Analysis of Robustly Decoupled Car Steering System with Nonlinear Tire Model", IEE, Proc. of the 36th Conference on Decision and Control, San Diego, California USA, December 1997.
- [11] Howard Dugoff, P. S. Fancher and Leonard Segel, "An Analysis of Tire Traction Properties and Their Influence on Vehicle Dynamic

Performance ” , SAE Transaction Journal, No.700377, 1970.

[12] Sven Kleine and Johannes L Van Niekerk, “ Modelling and Control of a Steer-by-Wire Vehicle ” , Vehicle System Dynamics Supplement, Vol.28, pp.114-142, 1998.

[13] Shibahata Y, Tomari T., “ Improvement of vehicle Maneuverability by Direct Yaw Moment Control ” , Vehicle System Dynamics, Vol.22, pp.465-481, 1993..

[14] Tong-Jin Park, Chang-Soo Han and Sang-Ho Lee, “ Development of the Electronic control Unit for the Rack-Actuating Steer-by-Wire Using the Hardware-in-the-Loop Simulation System ” , SDOS, Mechatronics 15, pp.899-918, 2005.

[15] X. Xia and E. H. Law, “ Nonlinear Analysis of Closed Loop Driver / Automobile Performance with Four Wheel Steering Control, ” SAE, No.920055, 1992.

[16] U. Kiencke and A.Daib, “ Observation of Lateral Vehicle Dynamics ” , SDOS, Vol.5, No.8, pp.1145-1150, 1997.

[17] Kunsoo Huh, Chanwon Seo, Joonyoung Kim and daegun Hong, “ Active Steering Control Based on Tire Estimated Tire Forces ” , Proceedings of American Control Conference, San Diego, California, June, 1999.

[18] Jin-Oh Hahn, Jae-Woong Hur, Soojoon Kang and Kyo Lee, “ Nonlinear Vehicle Stability Control Using Disturbance Observer ” , IEE, 2002.

[19] J. W. Post and E. H. Law, “ Modeling, Characterization and Simulation of Automobile Power Steering Systems for the Prediction of On-Center handling ” , SAE, No.960178, 1996.

[20] Masaki Yamamoto, “ Active Control Strategy for Improved Handling and Stability ” , SAE, No.911902, 1991.

[21] Werner Harter, Wolfgang Pfeiffer, Peter Dominke and Gerhard Ruck, “ Future Electrical Steering System: Realizations with Safety Requirements ” , SAE, Steering and Suspension Technology Symposium, 2000.

[22] Nicholas D. Smith, “ Understanding Parameters Influencing Tire Modeling ” , SAE, Department of Mechanical Engineering, Colorado State University, 2003.

[23] HASSAN K. KHALIL, “ Nonlinear System ” , Pearson Education International Inc. , 1996.

[24] Agoston L?rincz, “ Model Reference Control of a Steer-by-Wire Steering System ” , Budapest University of Technology and Economics, 2004.

[25] Sanjay Singh, “ Design of Front Wheel Active Steering for Improved Vehicle Handling and Stability ” , SAE, Proceeding of the Automotive Dynamics & Stability Conference, No.011619, 2000.

[26] 賴耿陽, “ 車輛驅動及控制 ” , 復漢出版社, 1995。