[1] L.X. Wang, " Adaptive fuzzy systems and control: Design and stability analysis," Englewood Cliffs, NJ: Prentice-Hall, (1994) [2] Y.C. Chang, " Adaptive fuzzy-based tracking control for nonlinear SISO systems via VSS and H-inf approaches," IEEE Trans. On Fuzzy systems , pp. 278-292. (2001) [3] C.S. Chen and W.L. Chen, " Robust model reference adaptive c control of nonlinear systems using fuzzy systems," I.J. of systems science, pp. 1435-1442. (1996) [4] C.Y. Su and Y. Stepanenko, " Adaptive control of a class of nonlinear systems with fuzzy logic, " IEEE Trans. On Fuzzy systems , vol.2, pp. 285-294. (1994).

[5] S. Tong and H.X. Li, " Fuzzy adaptive sliding-mode control for MIMO nonlinear systems," IEEE Trans. On Fuzzy systems , vol.11, No.3, pp. 354-360. (2003).

[6] C. Panchapakesan, M. Palaniswami, D. Ralph, and C.Manzie, " Effects of moving the centers in an rbf network, " IEEE Trans. on Neural Networks, vol.13, No.6, pp. 1299-1307. (2002), [7] H. Han, C.Y. Su, and Y. Stepanenko, " Adaptive control of a class of nonlinear systems with nonlinearly parameterized fuzzy approximators, " IEEE Trans. On Fuzzy systems , vol.9, No.2, pp. 315-323. (2001) [8] M. Maeda and S. Murakami, " A self-tuning fuzzy controller, " Fuzzy Sets and Systems, vol.51, pp.29-40. (1992) [9] Y.M. Park, U.C. Moon, and K.Y. Lee, " A self-organizing fuzzy logic controller for dynamic systems using a fuzzy auto-regressive moving average (FARMA) model, " IEEE Trans. On Fuzzy systems , vol.3, No.1, pp.75-82. (1995) [10] J.X. Xu and J. Xu, " A new fuzzy logic learning control scheme for repetitive trajectory tracking problems, " Fuzzy Sets and Systems, vol.133, pp.57-75. (2003) [11] L. Behera and K.K. Anand, " Guaranteed tracking and regulatory performance of nonlinear dynamic systems using fuzzy neural networks, " IEE Proc.-Control Theory Appl. , vol.146, pp.484-491. (1999) [12] C.J. Chien, " A sampled-data iterative learning control using fuzzy network design, " Internat. J. Control, vol.73, pp.902-913. (2000) [13] C. T. Lin and C.S.G. Lee, " Neural network-based fuzzy logic control and decision system, " IEEE Trans. Comput, vol.40, pp. 1320-1336. (1991) [14] K.S. Narendra and A.M. Annaswamy, " A new adaptive law for robust adaptation with persistent excitation, " IEEE Trans. On Automation control, vol.32, No.2, pp. 134-145. (1987) [15] S.Sastry and M.Bodson, " Adaptive control:stability, convergence and robustness " Englewood Cliffs, NJ:Prentice-Hall, (1989) [16] G.C. Goodwin and D.Q. Mayne, " A parameter estimation perspective of continuous time model reference adaptive control, " Automatica, vol.23, No.1, pp. 57-70. (1987) [17] G.P. Liu, V. Kadirkamanathan, and S.A. Billings, " Variable neural networks for adaptive control of nonlinear systems, " IEEE Trans. On systems, man, and cybernetics-Part C vol.29, No.1, pp. 34-43. (1999) [18] J.E. Slotine and W. Li, " Applied nonlinear control ," Englewood Cliffs, NJ: Prentice-Hall, (1991) [19] L.X. wang and J.M. Mendel ," Fuzzy basis function ,universal approximation , and orthogonal least squares learning" ,IEEE Trans. Neural Networks, Vol.3, pp.807-814, (1992) [20]          "          " (1995) [21]          "

"  2004          (2001)