

# Robust Cruise Control and Active Suspension System for the High Speed Train

徐萬權、林志哲

E-mail: 9314963@mail.dyu.edu.tw

## ABSTRACT

High speed train is a vehicle system which can be operated at least 200 km/hr. To make sure the safety and comfort at such high speed, the automatic train controller is needed to control and monitor the HST system. In Taiwan, the curved track is unavoidable due to the mountainous topography; thus the stability of the control system is very important. The control system of high speed train can be classified into three systems such as: the motion-planning system, the cruise control system and the active suspension system. In this paper, the cruise control system and active suspension system are studied; finally, the proposed controller is validated in the simulations of the simplified HST model and the whole train model of ADAMS.

Keywords : HST, Cruise Control, Active Suspension System, Sliding control, Automatic train control

## Table of Contents

封面內頁 簽名頁 授權書.....	iii	中文摘
要.....	v	英文摘要.....
vi 誌謝.....	vii	目
錄.....	viii	圖目
錄.....	x	表目
錄.....	xiii	第一章 緒
論.....	1	1.1 前言.....
回顧.....	3	1.2 文獻
鐵路列車模型建立.....	6	2.1 第二章 高速
器之模型.....	7	2.1.1 耦合
模型.....	8	2.1.2 HST之外擾與不確定性.....
立.....	10	2.1.3 HST之簡化數學
立.....	10	2.2 高速鐵路列車之全車模型建立.....
立.....	11	2.2.1 單節全車模型外觀建
制.....	13	2.2.2 懸吊系統建立.....
制.....	16	2.2.3 ADAMS全車模型建
簡化模型).....	24	3.1 傳統順滑控
順滑層之切換控制律.....	30	3.2 可變結構之模態追隨控制.....
.....	34	3.3 巡弋控制器模擬(
型.....	38	3.3.1 傳統順滑控制器+傳統切換控制律.....
擬(1/4車mode).....	45	3.3.2 傳統順滑控制器+具有
望.....	45	3.3.3 可變結構模態追隨控制.....
向.....	48	3.4 巡弋控制器模擬(ADAMS Model)
	48	4.1 1/4HST懸吊系統模
	50	4.2 全域順滑控制器.....
	50	4.2.1 全域順滑控制器模
	55	4.3 高速鐵路列車之全車模擬.....
	64	5.1 結論.....
	64	5.2 未來研究方
	65	5.1 結論.....
	65	參考文獻.....
	66	66

## REFERENCES

- [1] Hertz, H., "U & ber die Berührung fester elastischer Körper," -Angewandte Math. Crelle 92, pp. 155-171, 1882.
- [2] Carter, F. W., "On the Action of a Locomotion Driving Wheel," -Proc. R. Soc. London. A112, pp. 151-157, 1926.
- [3] Kalker, J.J., "On the Rolling Contact of Two Elastic Bodies in the Presence of Dry Friction," Thesis, Delft, 1967.
- [4] Kalker, J.J., "Simplified Theory of Rolling Contact," Delft Progress -Report1, vol.5, pp. 317-358, 1973.
- [5] Kalker, J.J., "A Fast Algorithm for the Simplified Theory of Rolling Contact," Vehicle System Dynamic, pp. 1-13, 1982.
- [6] Zboinski, K., "Dynamical investigation of railway vehicles on curved track," Eur. J. Mech. A/Solid, 17, pp. 1001-1020, 1998.
- [7] Haque, I. And Leih, J., "Parameterically Excited Behavior of a Railway Wheelset," J. of Dynamic Systems Measurement, and Control, ASEM, Vol.110, pp. 8-17, 1988.
- [8] 張世福, "非線性接觸力對於行駛於彎曲軌道車輛系統之動態穩定性效應," 成功大學機械工程所碩士論文, 2001.
- [9] 徐正會, 許益誠, "積極滾動控制之車輛半主動式懸吊系統之設計與分析," 中華名國第二十屆機械工程研討會, 2003.

- [10] 徐正會, 馬光杰, “ 軌道車輛單軸轉向架之分類與分析, ” 中華名 國第二十屆機械工程研討會, 2003.
- [11] 徐正會, 楊瑋弘, “ 軌道車輛自導式轉向架之研發, ” 中華名國第 二十屆機械工程研討會, 2003.
- [12] 徐正會, 李明晟, “ 軌道車輛可傾式轉向架之創新設計, ” 中華名 國第二十屆機械工程研討會, 2003.
- [13] ISO, “ Mechanical vibration - Measurement and analysis of -vibration to which passengers and crew are exposed in railway -vehicles, ” ISO10056, 1996.
- [14] ISO, “ Mechanical vibration and shock - Evaluation of human -exposure to whole-body vibration - Part4:Guidelines for the -evaluation of the effects of vibration and rotational motion on -passenger and crew comfort in fixed guideway transport system, ” -ISO2631-4, 1999.
- [15] Andersson, E., and Nilstam, N., “ The development of advanced -high speed vehicles in Sweden, ” Proceedings of the Institution of -Mechanical Engineers, Part D, 198(15), pp.229-237, 1984.
- [16] Chappel, T., “ Passenger comfort test (APT) of April 1984: -Planning and conduct, ” BRR TR DOS 036, British Rail Research, -1986.
- [17] Harborough, P. R., “ Passenger comfort during high speed -curving:Analysis and conclusions, ” BRR TR DOS 017, British -Rail Research, 1986.
- [18] Koyanagi, S., “ Ride quality evaluation of a pendulum car, ” -Quarterly report of RTRI, 26:3, pp.89-92, 1985.
- [19] Suzuki, H., Shioto, H., Tanka, A., Tezuka, K., Nakagawa, S., - “ Effects of vibrational factors on riding comfort evaluation of -tilting train passing curve transitions, ” In proceedings of World -Congress on Railway Research (WCRR ' 99), Tokyo, 1999.
- [20] Ohno, H., “ What aspect is needed for a better understanding of tilt -sickness?, ” Quarterly report of RTRI, 37(1), pp.9-13, 1996.
- [21] 孫允平, “ 混何 ¥ H H / 2 控制器設計及其應用:高速鐵路列車巡 弋控制及微衛星姿態控制, ” 成功大學航空大空工程研究所博 士論文, 2001.
- [22] Pratt, I., and Goodall, R., “ Controlling the ride quality of the -central portion of a high-speed railway vehicle, ” American -Control Conference, 1997. Proceedings of the 1997, pp.719-723 -vol.1.
- [23] Fukao, T., Yamawaki, A., Adachi, N., “ Adaptive control of -Partially Known Systems Usin Backstepping:Application to ¥ H -Design of Active Suspension, ” Decision and Control, 1998. -Proceedings of the 37th IEEE Conference on, pp.481-486 vol.1.
- [24] Sasaki, K., Kamoshita, S., Enomoto, M., “ A design and bench test -of multi-modal active suspension of railway vehicle, ” Industrial -Electronics, Control and Instrumentation, 1994. IECON '94., 20th -International Conference on , pp.2011-2016 vol.3.
- [25] Mei, T. X., Foo, T. H. E., Goodall, R. M., “ Genetic algorithms for -optimising active controls in railway vehicles, ” Optimisation in -Control:Methods and Applications (Ref. No. 1998/521), IEE -Colloquium on, 10 Nov. 1998.