

電流變液半主動式承載系統研究

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摘要

智慧型車輛已是下一世代道路運輸工具主要發展方向之一，而整個智慧型車輛系統中，行車通訊管理、車輛動力與動態控制、安全裝置及駕駛舒適度的提升等，都是不可或缺的一環。本論文主要目標在於研究提高行車舒適度的核心技術，我們使用電流變液為工作流體來設計避震器，以電流變液半主動式承載系統提高行駛之穩定性及過彎之操控性，以提升承載系統之功能。首先我們推導一2D與3D全車系統動態方程式，並以Fortran程式建立一2D與3D全車模擬系統，導入車體各種性能參數，模擬車身加速、減速、撞擊及過彎等行駛狀況，可供作設計避震器之參考。最後，我們製作出一組可安裝於實車上之電流變液半主動式承載系統，系統包含其控制電路與避震器本體，並進行安裝於實車性能測試，以取代原車傳統避震器，並提供承載系統之功能。

關鍵詞：智慧型車輛、半主動式承載系統、電流變液避震器

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