

# Assembly theory to large part number assembly product : exemplified by the motorcycle's engine

朱大明、鄧志堅

E-mail: 8809449@mail.dyu.edu.tw

## ABSTRACT

Rarely thoughts are put on the inspection of works in process and maintainability of the product during its development. Planning out the assembly sequences in advance, we can solve the problem above. Moreover, considering the machining constraints and the geometric features of the product, we can further reduce the production cost. This research deals with the generation of the assembly sequences of a product using portable razor and motorcycle 's engine as examples. We first analyze the precedence constraints of the liaisons, then build the liaison diagram and the looping constraints to generate all possible assembly sequences. Due to enormous routes of assembling the product, we further put the unconnected parts constraint to reduce the solution size. The unconnected part constraint is not the only choice to trim down the solution size. We may add more constraints such as machining, production layout and preference of the job site managers to make the production adaptable. Our program is written in JAVA.

Keywords : Liaison ; Geometric Constraints ; Looping Constraints ; Unconnected Parts

## Table of Contents

封面內頁 簽名頁 授權書 iii 中文摘要 iv 英文摘要 v 誌謝 vi 目錄 vii 圖目錄 ix 表目錄 xv 第一章 緒論 1 1.1 研究背景與動機 1 1.2 研究目的與範圍 2 1.3 研究架構 4 1.4 研究方法 6 第二章 文獻探討 7 第三章 演算法 13 3.1 幾何限制式 13 3.2 產品迴圈限制式 15 3.2.1 建構展開樹 17 3.2.2 尋找基本迴圈 18 3.2.3 產所有迴圈 19 3.2.4 選擇非重複迴圈 21 3.3 非連結性零件 25 第四章 旅行用刮鬍刀之實例驗證 27 4.1 幾何限制式之應用 29 4.2 非重複迴圈之應用 36 4.3 產生所組裝順序 38 4.4 非連結性零件之應用 39 4.5 幾何限制式之修正 43 第五章 機車引擎之實例驗證 48 5.1 問題簡化 49 5.2 機車引擎零件次組合1 51 5.3 機車引擎零件次組合2 58 5.4 機車引擎零件次組合3 64 5.5 機車引擎零件次組合4 71 5.6 完成機車引擎組裝 77 5.7 執行時間測試 94 第六章 結論 99 參考文獻 101

## REFERENCES

1. 經濟部生產自動化執行小組，中華民國第五次生產自動化報告（1990）。
2. Bourjault, A., " Contribution a une Approche Methodologique de l'Assemblage Automatise: Elaboration Automatique des Sequences Operatoires, " Thesis to obtain Grade de Docteur es Sciences Physiques at L'Universite de Franche-Comte, Paris(1984).
3. De Fazio, T. and D. Whitney, " Simplified Generation of all Mechanical Assembly Sequences, " IEEE Journal of Robotics and Automation, Vol. RA-3, No. 6, pp. 640-658 (1987).
4. De Fazio, T. and D. Whitney, " Correction to "Simplified Generation of all Mechanical Assembly Sequences", " IEEE Journal of Robotics and Automation, Vol. RA-3, No. 6, pp. 705-708 (1987).
5. Abel, T.E., " An Interactive Software Tool for Editing and Evaluating Mechanical Assembly Sequences Based on Fixturing and Orientation Requirements, " S.M. Thesis, M. I. T., Mechanical Engineering Department, Cambridge, MA, (1989).
6. Homem de Mello, L.S. and A.C. Sanderson, " AND/OR Graph Representation of Assembly Plans, " IEEE Transactions on Robotics and Automation, Vol. RA-6, No. 2, pp. 188-199 (1990).
7. Homem de Mello, L.S. and S. Lee, " Computer-Aided Mechanical Assembly Planning, " Kluwer Academic Publishers, Boston, MA (1992).
8. Lui, M.M., " Generation and Evaluation of Mechanical Assembly Sequences Using the Liaison-Sequence Method, " S.M. Thesis, Department of Mechanical Engineering, M.I.T., Cambridge, MA (1988).