

# Study of Reconfigurable Machine Tool-Design and Manufacturing

巫崇璋、賴元隆, 紀華偉

E-mail: 386809@mail.dyu.edu.tw

## ABSTRACT

The demand for efficiency and precision of CNC grows with advancing technology. From 3-axis to 4 or 5-axis machines are built to meet industrial demands, so does the number of studies and literatures regarding reconfigurable machine tools. The application of configurable units is between dedicated units and multifunctional CNCs. Dedicated units are selected for pieces to be machine for single products of mass production. If the pieces are in small quantity and large variety, highly priced multifunctional CNCs are a good choice. For other types of machining, the configurable machine tools may be considered. They have the potential of development and worth in-depth investigation and study in this regard. This paper is intended to focus on the development of reconfigurable modules of machine tool. First the modular categories of machine tool parts and components are established based on functions, kinetics and assembly needs. Then, introduction is given on how to separate the unit into primary and secondary modules from the point of view of direction from which the flow of force is directed, and unfit modules are eliminated from a selection of modules. Modules that meet the criteria are identified using this series of selection steps, and finally a limitation equation is brought in to identify machine tool modules that fit the cost function the most. By employing this sequence, designers will be able to come up with the best-fit module combination from a module library based on various needs, thus eliminating the need to redesign and redevelop a unit of the same specifications. It requires the replacement of necessary modules to modify the entire unit and no need for redesign, saving both time and cost. A modular method was introduced to simulate the establishment of a configurable unit. Preliminary structure design was performed after confirmation of specifications. Calculations were made to determine suitable key components, such as threaded rods and linear guideways, that meet precision requirements. For the selection of machining process, suppliers are sought out to satisfy the demands for costs and delivery deadlines. Parts and components to be machined are scrutinized for tolerance based on design drawings. After measurement, parts and components are placed in warehouse by categories. Standard assembly procedures and machine checklists are established to facilitate the assembly based on standard procedures and ensure the errors accumulated from allowable tolerance within control. The unit is energized and laser interferometer is used for positioning compensation. Circular tester is used for roundness test in order to meet the requirement of co-action interpolation error. Finally D-H modified notation is introduced for coordinate conversion program. CC path is converted to CL path to produce NC Code of machining. NC Code is imported into the control for machining and the precision of finished products is measured to make sure that the requirements of dimension in the design are met.

Keywords : modular、 five-axis、 D-H modified notation

## Table of Contents

中文摘要.....	iii	ABSTRACT.....	v	誌謝.....	vii	目錄.....	viii	圖目	
錄.....	x	表目錄.....	xiii	第一章 緒論.....	1	1.1前言.....	1	1.2研究動機與目	
的.....	2	1.3文獻回顧.....	3	1.4論文架構.....	4	第二章 D-H修正標記法應用於加工機台.....	7	2.1齊	
次轉換矩陣.....	7	2.2 D-H 修正標記法.....	9	2.3 螺旋理論.....	11	2.4 圖形理論.....	18	第	
三章 可重組式運動模型建構.....	22	3.1 機台模型建構.....	22	3.2機台運動誤差.....	28	3.3 機台選用範		例	
.....	33	第四章 機台組裝檢測及加工驗證 .....	40	4.1機台組裝、 檢測.....	40	4.2後處理器概		述	
.....	45	4.3NC碼加工與驗證.....	46	4.3.1實際加工.....	46	4.3.2加工點驗證.....	52	第	
五章 結論與未來展望.....	60	5.1 結論.....	60	5.2 未來展望.....	61	參考文		獻	
.....	62								

## REFERENCES

- [1]Denavit J., Hartenberg R.S.(1955). A Kinematic Notation for Lower pair Mechanisms Based on Matrices, Journal of Applied Mechanics, 215-221.
- [2]Lin P. D., Chen J.F. (1994). Analysis of Error in Precision for Closed Loop Mechanisms , Journal of Mechanical Design, March, Vol.116,197-203.

- [3]Kenneth W., James S.(2008). Schmieider: Kinematics. Springer Handbook of Robotics, 9-33.
- [4]Tilbury D.M., KotaS.(1999). Integrated Machine and Control Design for Reconfigurable Machine Tools. IEEE/ASME ,629- 634.
- [5]Nasser A.(2011). Reconfigurable Machine Tools Design Methodologies and Measuring Reconfigurability for Design Evaluation. Thesis of Master ,The Royal Institute of Technology, Sweden .
- [6]Padayachee J., Bright G. (2012).Modular machine tools: Design and barriers to industrial implementation. Journal of Manufacturing Systems, Vol.31,92-102.
- [7]Yong M.M.(2002) Design of Reconfigurable Machine Tools. ASME, Vol.124, 480-483.
- [8]Lin Y., Shen Y.(2003). Modelling of Five-Axis Machine Tool Metrology Models Using the Matrix Summation Approach. Int J Adv Manuf Technol, Vol.21, 243- 248.
- [9]邱國峰(2011)。五軸工具機之電腦模擬機構建立。碩士論文，大葉大學，彰化。
- [10]吳孟霖(2007)。五軸加工後處理程式之建構與應用。碩士論文，國立台北科技大學，台北。
- [11]鄒震羸(2006)。應用 OpenGL 於五軸虛擬工具機系統之發展。碩士論文，國立成功大學，台南。
- [12]吳錫章(2007)。非正交型車銑複合虛擬工具機運動模型系統之發展。碩士論文，國立成功大學，台南。
- [13]郭禮安(2008)。利用D-H修正標記法於非正交多軸工具機自動化泛用型後處理程式之發展。碩士論文，國立成功大學，台南。
- [14]Aini A.K., Xun X., Enrico.H.(2011). Virtual Machine Tools and Virtual Machining —A Technological Review. Robotics and Computer-Integrated Manufacturing, Vol.27,494-508.
- [15]Abdul W.K., Chen W.(2010) .Systematic Geometric Error Modeling for Workspace Volumetric Calibration of a 5-axis Turbine Blade Grinding Machine. Chinese Journal of Aeronautics, Vol.23, 604-615.
- [16]Abdul W.K.,Chen W.(2010). Systematic Geometric Error Modeling for Workspace Volumetric Calibration of a 5-axis Turbine Blade Grinding Machine. Chinese Journal of Aeronautics , Vol.23, 604-615.
- [17]王靖霽(2002)。三軸工具機誤差分析與量測。碩士論文，國立成功大學，台南。
- [18]Luiz R., Roberto S., Edson Roberto De Pieri., Daniel Martins.(2012). A Comparative Study of the Kinematics of Robots Manipulators by Denavit-Hartenberg and Dual Mecanica Computacional, Vol.31,2833- 2848.
- [19]Conrad K.L., Panayiotis S., Shiakolas., Yih T.C.(2000). Robotic Calibration Issues:Accuracy, Repeatability and Calibration. the 8th Mediterranean Conference on Control & Automation.
- [20]Schultschik R.(1997).The Components of Volumetric Accuracy. Annals of CIRP,Vol.26.
- [21]黃泓欽(2007)。五軸虛擬工具機系統之技術研究。碩士論文，國立中正大學機械工程研究所，嘉義。
- [22]Kiridena V.S.B.,Ferreira P.M.(1994).Kinematic Modelling of Quasistatic Errors of Three-Axis Machining Centers.Int. J.Mach. Tools Manufact, Vol.34,1.68,85- 100.
- [23]Lin Y.Z.,Shen Y.L.(2004).Enhanced Virtual Machining for Sculptured Surfaces by Integrating Machine Tool Error Model into NC Machining Simulation. International Journal of Machine Tool & Manufacture, Vol.44,79-86.
- [24]Suh S.H.,Lee K.S.(1991).A Prototype CAM System for Four -axis NC Machining of Rotational-Free- Surfaces. Journal of Manufacturing Systems, Vol.10,322-331.
- [25]許博榕(2012)。五軸工具機之線性傳動機構。碩士論文，大葉大學，彰化。