

Design and Implementation of the Monitoring System for the Vehicle Dual Braking System Testbench

張俊智、張舜長

E-mail: 364775@mail.dyu.edu.tw

ABSTRACT

With the vigorous progress of vehicle technology industry, people pay more attention on the road safety nowadays. Based on the braking system directly relating to the safety of drivers, the relative studies of its dual braking system have comparatively brought up the importance as well. The purpose of this study is to explore the setting of simulating platform of dual braking system as well as the functional response, and to test the hydraulic source of the dual braking system. Its aim is to utilize the function of braking system in designing a braking simulating platform, design a dynamic real time monitoring interface according to the platform built with LabVIEW graphic software, and then discuss the dual braking system of its functional response. LabVIEW graphical control software program the vehicle dual braking system for moving response. And brake simulation test platform, which the simulation of the vehicle walking, each sensor's signal source, and control. The test results indicated that, vehicle dual braking systems program monitoring, for the dynamic response can immediately follow the changes in the brake hydraulic response and actuation.

Keywords : dual braking system、 LabVIEW

Table of Contents

封面內頁 簽名頁 中文摘要.....iv	ABSTRACT.....v	誌謝.....vi	目錄.....vii	圖目錄.....ix	表目錄.....x	符號說明.....xi	第一章緒論.....1
1.1前言.....1	1.2研究動機.....2	1.3文獻回顧.....4	1.4 本文架構.....8	第二章車輛雙煞車系統架構簡介.....10	2.1 煞車系統概要.....10	2.1.1傳統液壓煞車系統介紹.....10	2.2 車輛雙煞車系統介紹.....14
2.3 車輛雙煞車系統平台設計.....15	2.3.1車輛雙煞車測試平台的基本原理.....16	第三章雙煞車監控系統設計與分析.....17	3.1監控介面系統設計方向.....17	3.1.1LabVIEW環境介紹.....18	3.1.2雙煞車系統測試平台監控系統之建立.....21	3.2雙煞車監控系統相關公式引用與說明.....24	第四章實驗結果與分析.....32
第五章結論與建議.....41	5.1結論.....41	5.2建議事項與未來研究方向.....42	參考文獻.....43				

REFERENCES

- [1]W. K. Lennon, and K. M. Passino, " Intelligent Control for Brake Systems, " IEEE Transaction on Control Systems Technology., Vol. 7, No. 2, pp. 188-202, March, 1999.
- [2]N. R. Trevett, " X-by-Wire, New Technologies for 42V Bus Automobile of the Future, " South Carolina Honors College, 2002.
- [3]黃靖雄, " 汽車學(二)-底盤篇, " 全華科技圖書股份有限公司, 2002.
- [4]A. Sornioti, " Hardware in the Loop for Braking System with Anti-Lock Braking System Electronic Stability Program, " SAE Technical paper, No. 2004-01-2062.
- [5]廖雲霞, " 制動器慣性試驗臺架的研究與開發, " 長安大學, 車輛工程研究所碩士論文, 2006.
- [6]K. Bill, M. Semsch, and B. Breuer, " A New Approach to Investigate the Vehicle Interface Driver/Brake Pedal Under Real Road Conditions in View of Oncoming Brake-By-Wire Systems, " SAE Technical Papers, No. 1999-01-2049.
- [7]J. C. Lee, and M. W. Suh, " Hardware-in-the Loop Simulator for ABS/TCS, " IEEE Transaction on Control Systems Technology., Vol. 1, pp. 652-657, August, 1999.
- [8]F. Yuan, G. V. Puskorius, L. A. Feldkamp, and L. I. Davis, " Neural Network Control of a Four-Wheel ABS Model, " IEEE Transaction on Control Systems Technology., Vol. 2, pp. 1503-1506, August, 1995.
- [9]T. Nakashima, " Promotion of the Program of Advanced Safety Vehicle for 21st Century, " JSAE Review, Vol. 16, pp. 3-6, 1995.
- [10]M. L. Kuang, M. Fodor, D. Hrovat, and M. Tran, " Hydraulic Brake System Modeling and Control For Active of Vehicle Dynamics, " Proc. of the American Control Conference., Vol. 6, pp. 4538-4542, 1999.
- [11]H. Klode, A. M. Omekanda, and B. Lequesne, " The Potential of Switched Reluctance Motor Technology for Electro-Mechanical Brake Applications, " SAE Technical Papers, No. 2006-01-0296.
- [12]G. F. Mauer, " A Fuzzy Logic Controller for an ABS Braking System, " IEEE Transactions on Fuzzy Systems, Vol. 3, No. 4, pp. 381-388, November, 1995.
- [13]A. Krueger, D. Kant, and K. Buhlmann, " Software Development Process and Software Components for X-by-wire Systems, "

SAETechnical Papers, No. 2003-01-1288.

- [14]N. Mutoh, Y. Hayano, H. Yahagi, and K. Takita, " Electric Braking Control Methods for Electric Vehicles with Independently Driven Front and Rear Wheels, " IEEE Transaction on Industrial Electronics, Vol. 54, No. 2, pp.1168-1176, April, 2007.
- [15]P. M. de Koker, J. Gouws, and L. Pretorius, " Fuzzy Control Algorithm for Automotive Traction Control System, " IEEE Transaction on Control Systems Technology., Vol. 1, pp. 226-229, May, 1996.
- [16]S. K. Mazumdar, and C. C. Lin, " Investigation of the Use of Neural Networks for Anti-Skid Brake System Design, " IEEE Transaction on Control Systems Technology, pp. 505-510, 1995.
- [17]J. R. Layne, K. M. Passino, and S. Yurkovich, " Fuzzy Learning Control for Anti-skid Braking System, " IEEE Transaction on Control Systems Technology., Vol. 1, No. 2, pp. 2523-2528, December, 1993.
- [18]S. Drakunov, U. Ozguner, P. Dix, and B. Ashrafi, " ABS Control Using Optimum Search via Sliding Modes, " IEEE Transaction on Control Systems Technology., Vol. 3, No. 1, pp. 79-85, March, 1995.
- [19]S. V. Drakunov, B. Ashrati, and A. Rosiglioni, " Yaw Control Algorithm via Sliding Mode Control, " Proc. of the American Control Conference., Vol. 1, No. 6, pp. 580-583, 2000.
- [20]R. H. Innezhad, S. Saric, and A. Bab-Hadiashar, " Estimation of Clamp Force in Brake-by-wire System:A Step-by-step Identification Approach, " SAE Technical Papers, No. 2006-01-1154.
- [21]李華斌, " 車身動態穩定控制系統之硬體迴路模擬與實車驗證實驗 , " 大葉大學 , 機械工程研究所碩士論文 , 2008。
- [22]會汝生, " LabVIEW 8.X圖控程式應用 , " 全華圖書有限公司, 2008。
- [23]陳建次, " 電控煞車系統介紹 , " ARTC研發處底盤系統發展專案, 2007。
- [24]戴義國、王亞平與馮騰榔, " 機械元件設計 , " 文京圖書有限公司, 1982。
- [25]工程計算機要如何將rad/s換成角度。 <http://tw.knowledge.yahoo.com/question/question?qid=1405120808014>, 2011。
- [26]不只是槓桿原理, 細說油壓煞車。 <http://www.mobile01.com/topicdetail.php?f=318&t=382571>, 2011。
- [27]周靜娟、吳明瑞與顏培仁編著, 圖控程式與自動量測使用LabVIEW 7.X 修訂版 , " 全華科技圖書股份有限公司, 2008。
- [28]魯道夫 林佩特, 煞車系統設計及安全性煞車系統 第二版高維山譯 " SAE科技圖書, 2004。