

The study of motion control for high speed measuring system

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ABSTRACT

In this study, a high-speed measurement system was established by combining an open programmable logic controller (OPLC) from Fuji Electric Co., Ltd. with servo motors and sensor equipped on Z-axis. The distance between sensor and the surface of measuring part was detected by applying a gap controller. The gap controller was equipped for Z-axis of high-speed measurement system. The gap controller was programmed by using Structure Text for PLC. A root-mean-square error method was applied to evaluate and find out the optimized gap controller parameters. Finally, experiment results were achieved by taking experiment on this proposed high-speed measurement system. The experiment results show that the proposed system could be applied to practical manufacture.

Keywords : programmable logic controller、gap control、high-speed measurement system

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