

Performance comparison between applying the PHD filter and kalman filter to WSN

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ABSTRACT

In this thesis, the PHD (probability hypothesis density) filter and the Kalman filter are adopted as the two algorithms for tracking the maneuvering objects that deployed in the WSNs (wireless sensor networks) environments. The tracked performance with the RMSE (root mean square error) are compared each other and they are simulated by the computer programs. The superior performance can be obtained by the PHD filter is algorithm, however, the simple implementation of Kalman filter is outperform than PHD filter. For the purpose of gaining better performance to track maneuvering objects, the results from this thesis are good reference for the designing in deployment of the mobile sensors within WSNs.

Keywords : wireless sensor networks(WSNs) ; probability hypothesis density(PHD)filter ; Kalman filter ; root mean square error(RMSE).

Table of Contents

封面內頁 簽名頁 授權書.....	iii	中文摘要.....	iv
ABSTRACT.....	v	誌謝.....	vi
目錄.....	vii	圖目錄.....	ix
第一章 緒論.....	1	1-1 前言.....	1
1-2 研究動機與背景.....	3	1-3 論文結構.....	3
第二章 機率假定密度濾波器.....	4	2-1 機率假定密度濾波器簡介.....	5
2-2 高斯混合機率假定密度濾波器.....	5	2-3 粒子機率假定密度濾波器.....	8
2-4 互補濾波器與低通濾波器特性.....	14	第三章 卡門濾波器.....	16
3-1 卡門濾波器簡介.....	19	3-2 系統估計過程信號.....	19
3-3 計算原型的濾波器.....	21	3-4 卡門濾波器離散演算法.....	23
3-5 擴展式卡門濾波器.....	25	第四章 無線感測網路.....	29
4-1 無線感測網路簡介.....	37	4-2 IEEE 802.15.4 運用在無線感測器.....	37
4-3 無線感測網路硬體結構.....	39	4-4 無線感測網路的機制特性.....	43
第五章 模擬結果與討論.....	44	5-1 卡門濾波器模擬結果.....	48
5-2 卡門濾波器與PHD濾波器之比較.....	48	第六章 結論.....	54
參考文獻.....	62	圖目錄 圖2-1 機率動態系統.....	63
圖2-2 基本模型.....	9	圖2-3 互補濾波器架構.....	11
圖2-4 一階低通濾波器.....	17	圖3-1 卡門濾波器整體系統區塊圖.....	17
圖3-2 卡門濾波器方塊圖.....	19	圖3-3 離散卡門濾波器迴圈更新圖.....	21
圖3-4 工作原理由圖3.3和時間更新及狀態更新結合得到.....	26	圖3-5 線性化的卡門濾波軌跡.....	28
圖4-1 無線感測網路系統基本架構.....	33	圖4-2 IEEE 802.15.4 的架構示意圖.....	39
圖4-3 感測器的硬體結構.....	40	圖4-4 網路容錯重建機制.....	44
圖5-1 卡門濾波器單目標動態追蹤.....	45	圖5-2 卡門濾波器單目標均方根誤差.....	51
圖5-3 卡門濾波器兩個動態目標追蹤.....	51	圖5-4 卡門濾波器兩個動態目標均方根誤差.....	52
圖5-5 粒子濾波器估測週期.....	53	圖5-6 PHD濾波器單目標動態追蹤.....	54
圖5-7 PHD濾波器單目標動態均方根誤差.....	55	圖5-8 卡門濾波器產生不同的軌跡單目標動態追蹤.....	55
圖5-9 卡門濾波器不同的軌跡單目標動態均方根誤差.....	57	圖5-10 PHD濾波器兩個動態目標追蹤.....	59
圖5-11 PHD濾波器兩個動態目標均方根誤差.....	59	圖5-12 卡門濾波器不同的兩個動態目標軌跡.....	60
圖5-13 卡門濾波器不同的兩個動態目標軌跡均方根誤差.....	61	表目錄 表5-1 卡門濾波器單目標動態之數據.....	52
表5-2 卡門濾波器兩個動態目標之數據.....	53	表5-3 PHD濾波器單目標動態之數據.....	56
表5-4 卡門濾波器產生不同的軌跡單目標之數據.....	58	表5-5 PHD濾波器兩個動態目標之數據.....	60
表5-6 卡門濾波器不同的兩個動態目標之數據.....	61		

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