

The Research of Radar Tracking System Using Multiple Model Algorithm

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ABSTRACT

The multiple-target tracking algorithm plays an important role in a radar system. The key techniques for improving the tracking accuracy include data association and maneuvering estimation algorithm. In this dissertation, a data association denoted one-step conditional maximum likelihood algorithm is proposed to improve the tracking capability. Moreover, an improve algorithm denoted the adaptive multiple model estimator is developed in this dissertation. When target maneuvering movement is occurred, maneuver detection and acceleration estimation algorithms are applied to modify the parameters of the tracking filter. In this algorithm, a bank of Kalman filters is applied to improve the tracking accuracy of radar surveillance. Based on computer simulations, we can convince this approach will obtain the better tracking results.

Keywords : Adaptive Multiple Model Estimator、Data Association Technique、Kalman Filters

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